

SAFETY ASSURANCE BASED ON AN OBJECTIVE IDENTIFICATION OF SCENARIOS

One Approach of the PEGASUS-Project



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Supported by:



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PEGASUS Project

Project for Establishing Generally Accepted quality criteria, tools and methods as well as Scenarios And Situations for approval of **highly automated driving functions**



42 Month

2016 January 1st – 2019 June 20th

17 Partners



12 Subcontractors

i.a. IFR, ika, OFFIS

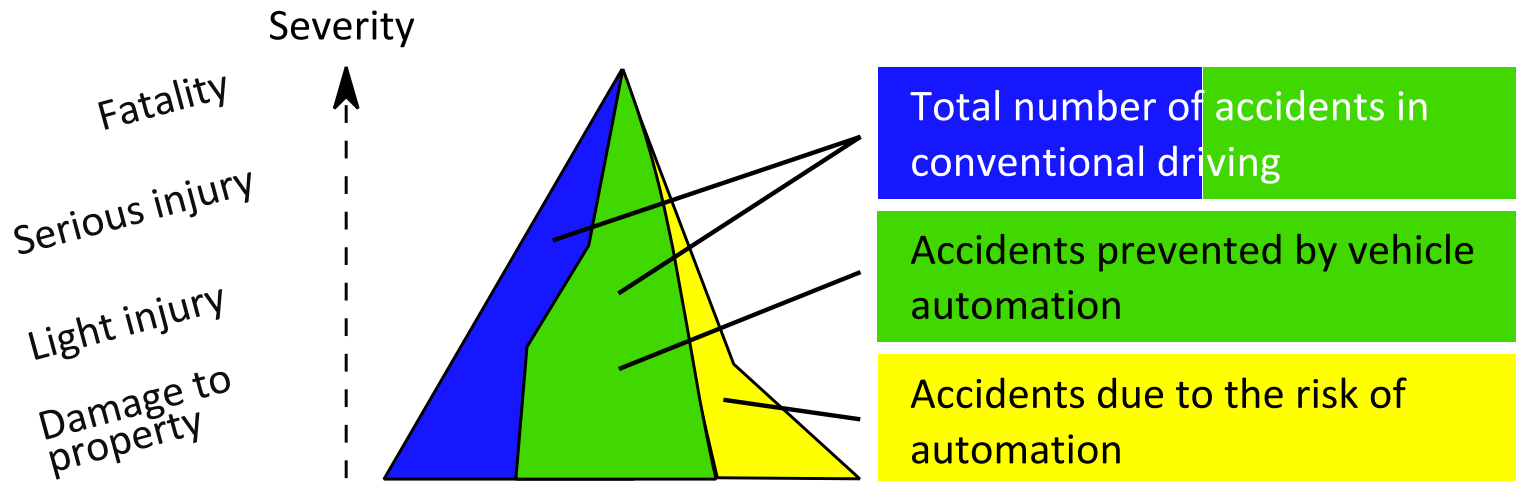
Projects budget

ca. 34.5 m. EUR, funding 16.3 m. EUR

Personnel planning

ca. 1,791 person month that is 149 person years

Safety Challenge for HAD (SAE level 3)



[1]

- Which change in numbers due to highly automated driving will occur?
- Do we need to predict the change for all level of severity?

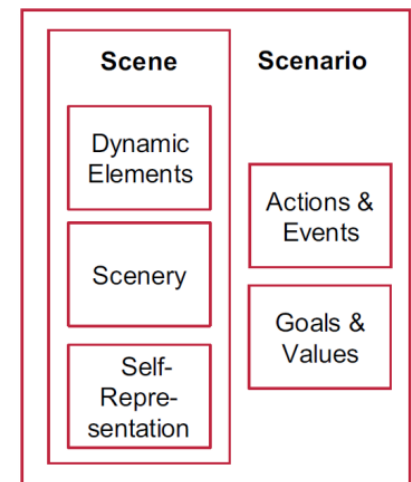
The proof of safety for the top of severity is economically not possible by a solely stochastic approach of real world driving. [1-4]

→The Approval-Trap asks for hundred millions or even billions of test kilometers.

- If we want to reduce the kilometers of real world driving, we have to identify relevant scenarios for alternative approaches!

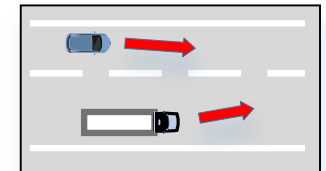
Scenario:

- “A **scenario** describes the **temporal development** between several scenes in a sequence of scenes. Every scenario starts with an **initial scene**. **Actions & events** as well as **goals & values** may be specified to characterize this temporal development in a scenario. Other than a scene, **a scenario spans a certain amount of time.**”



[5]

- A **concrete scenario** is a series of subjective or objective scenes, including **specific movement trajectories** of one or more vehicles, and the concrete description of **the environment**.
- A **logical scenario** is a **configurable representation** of the traffic with parameter distributions. Substituting individual parameter combinations concrete scenarios can be derived.

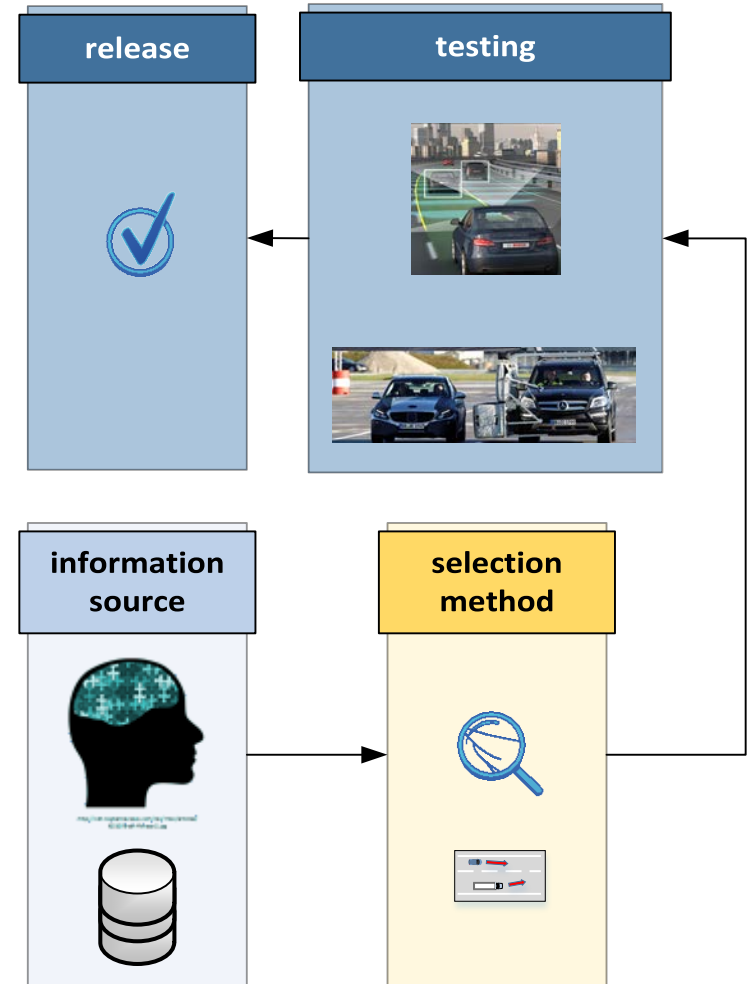


Method to Identify Scenarios and Assess Relevance

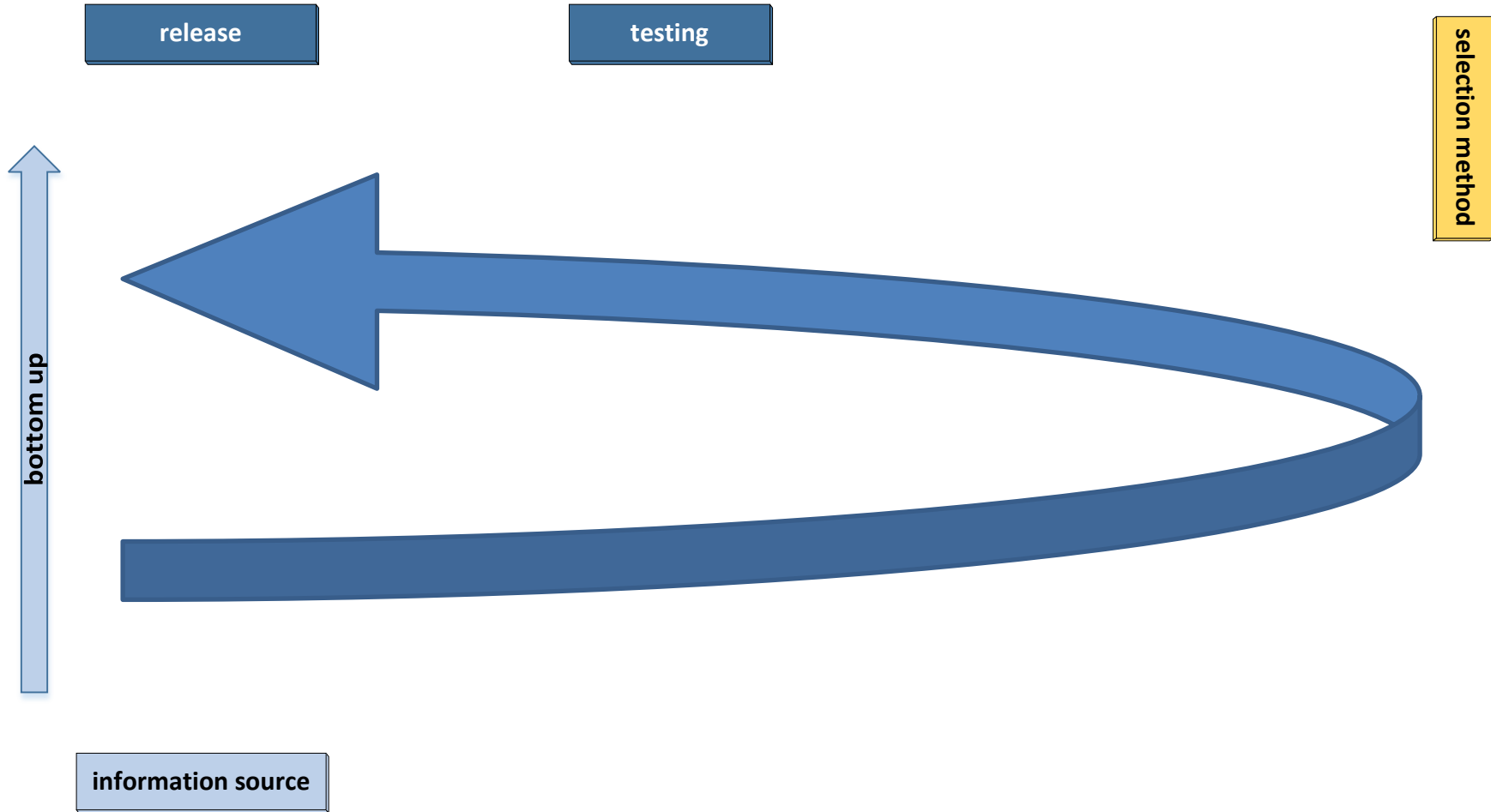
Let's start simple:



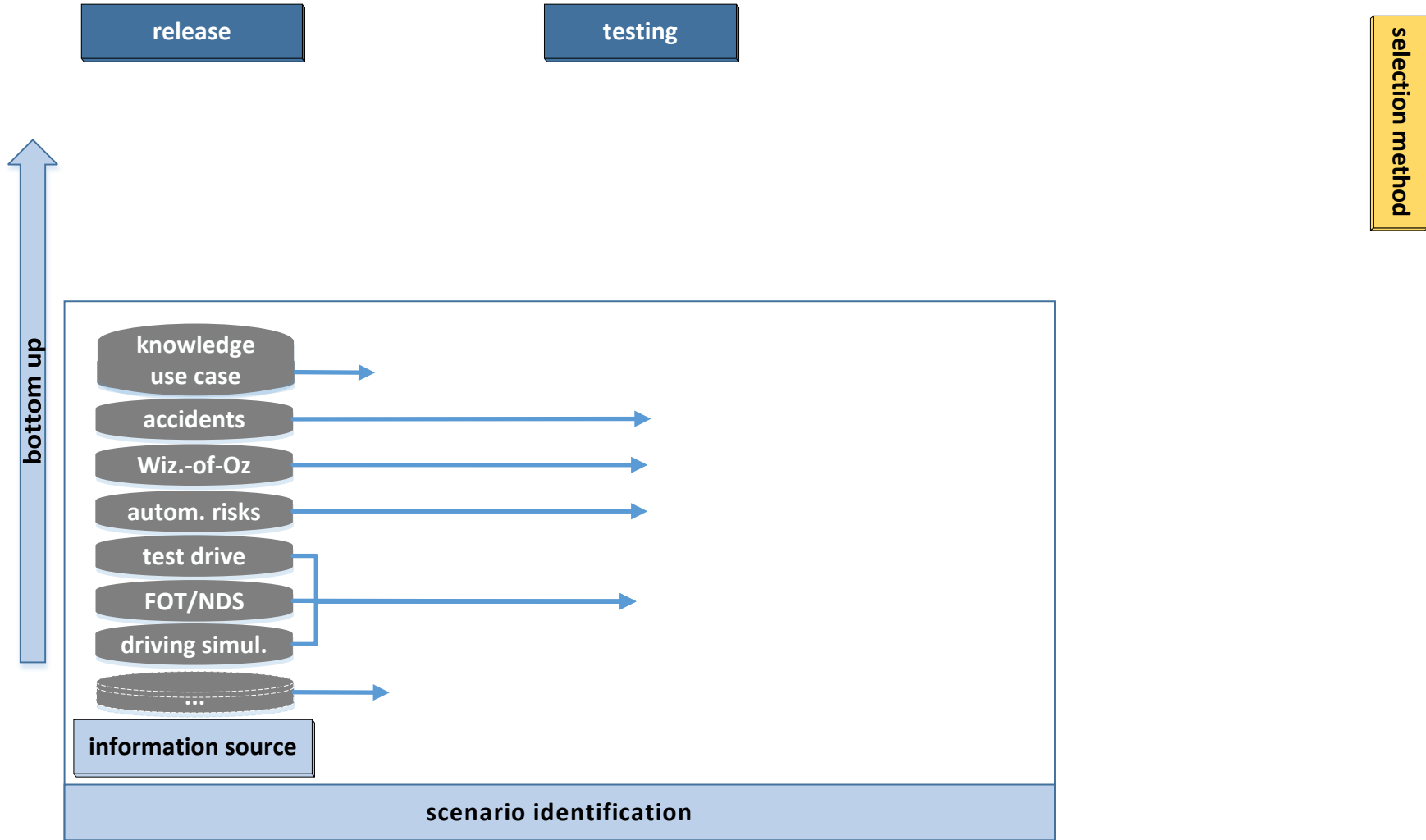
- The goal is to bring **HAD** to the users.
 - The process seems straight forward.
 - But every step needs a decision of an engineer/manager → human.
- To establish objective decisions, metrics should be identified and established.



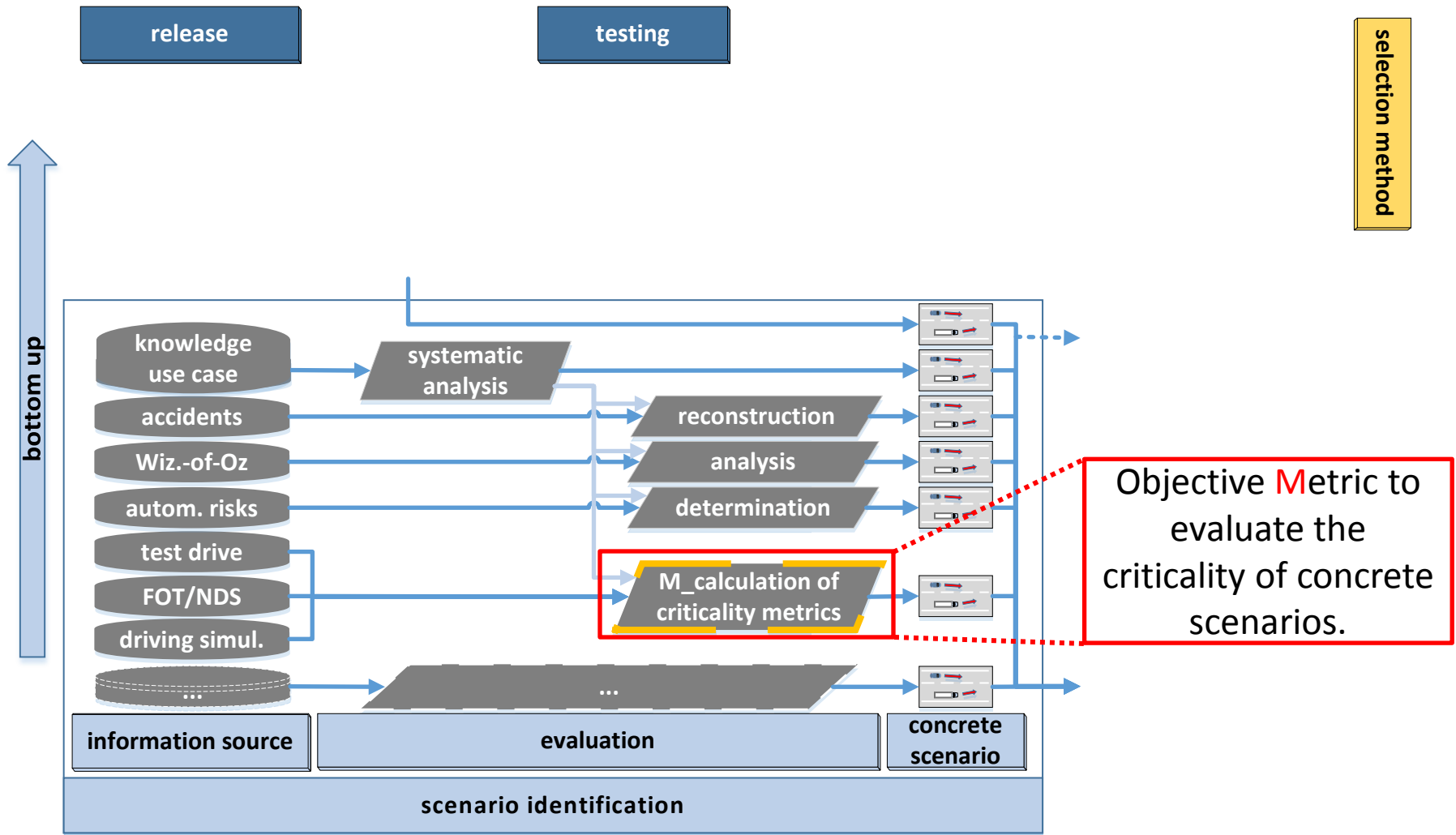
Method to Identify Scenarios and Assess Relevance



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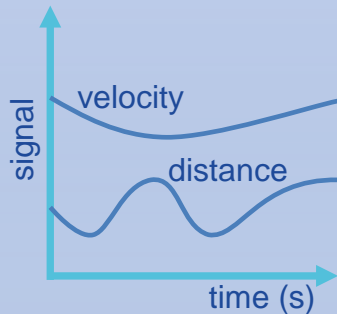
Metrics to Evaluate Information Sources

- calculation of criticality metrics -

Step 1

Collect measurement signals from:

- simulations
- accident analysis
- test site measures
- FOT data
- ...

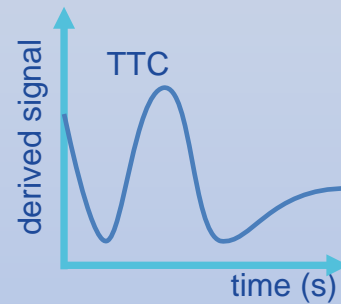


Step 2

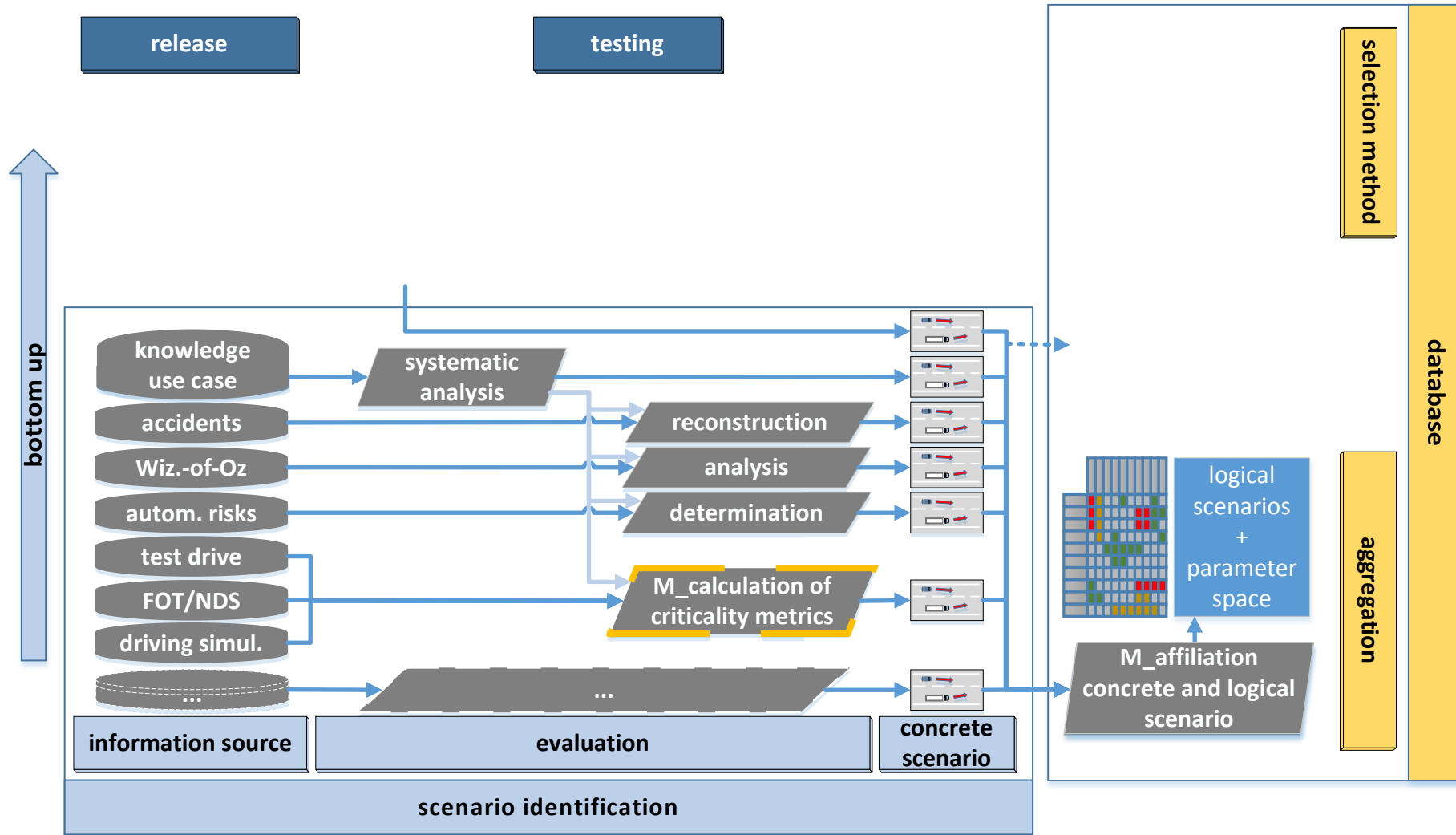
Derive additional signals in a coherent way

e.g.:

- time-to-collision
- time-headway
- ...

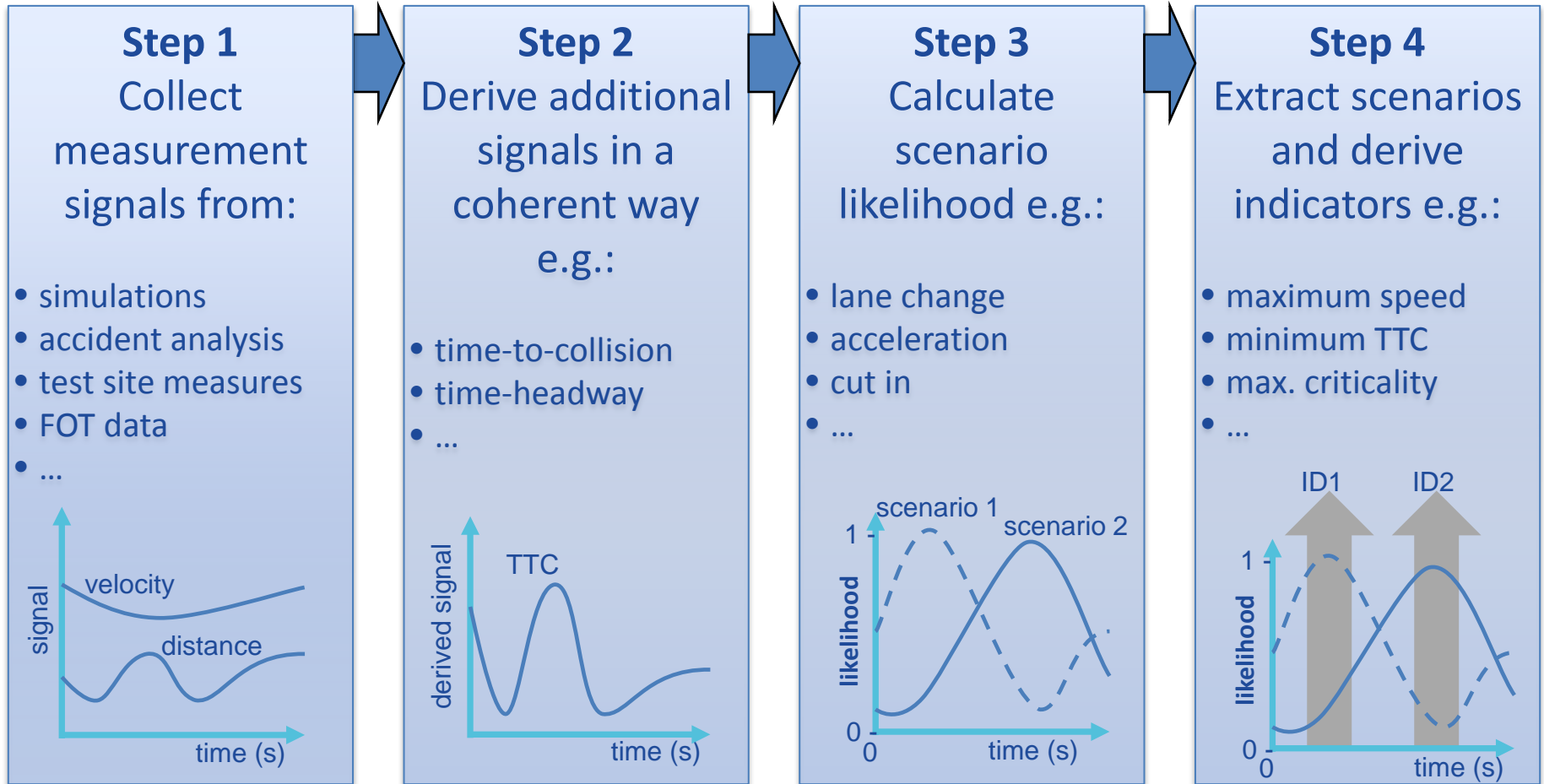


Method to Identify Scenarios and Assess Relevance



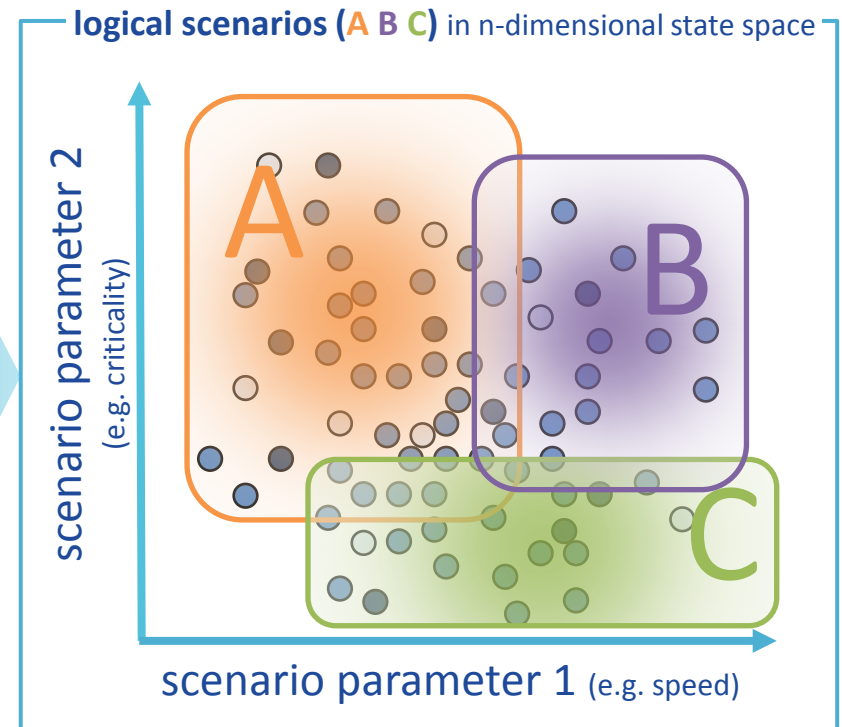
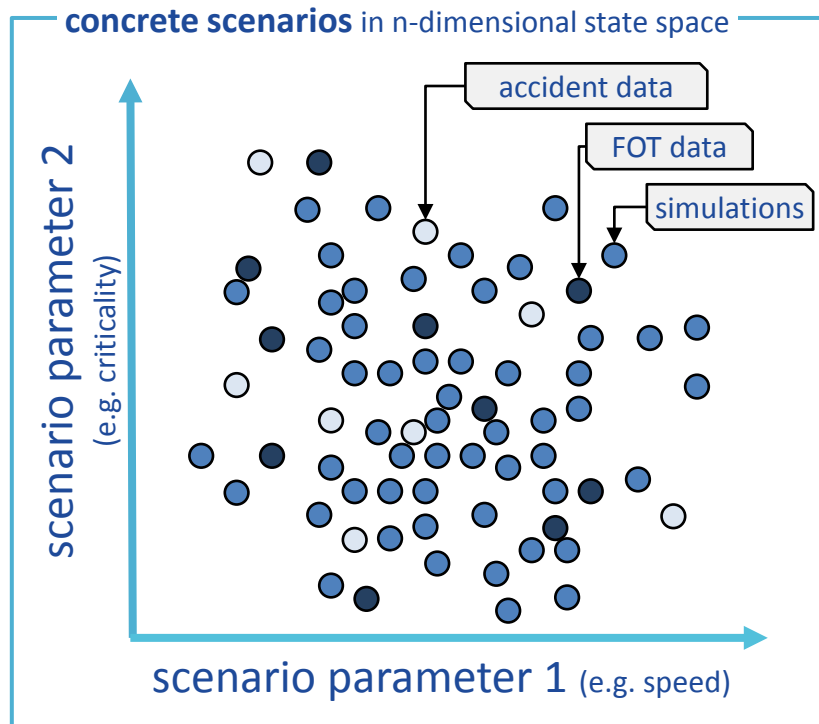
Metrics to Evaluate Information Sources

- calculation of criticality metrics -

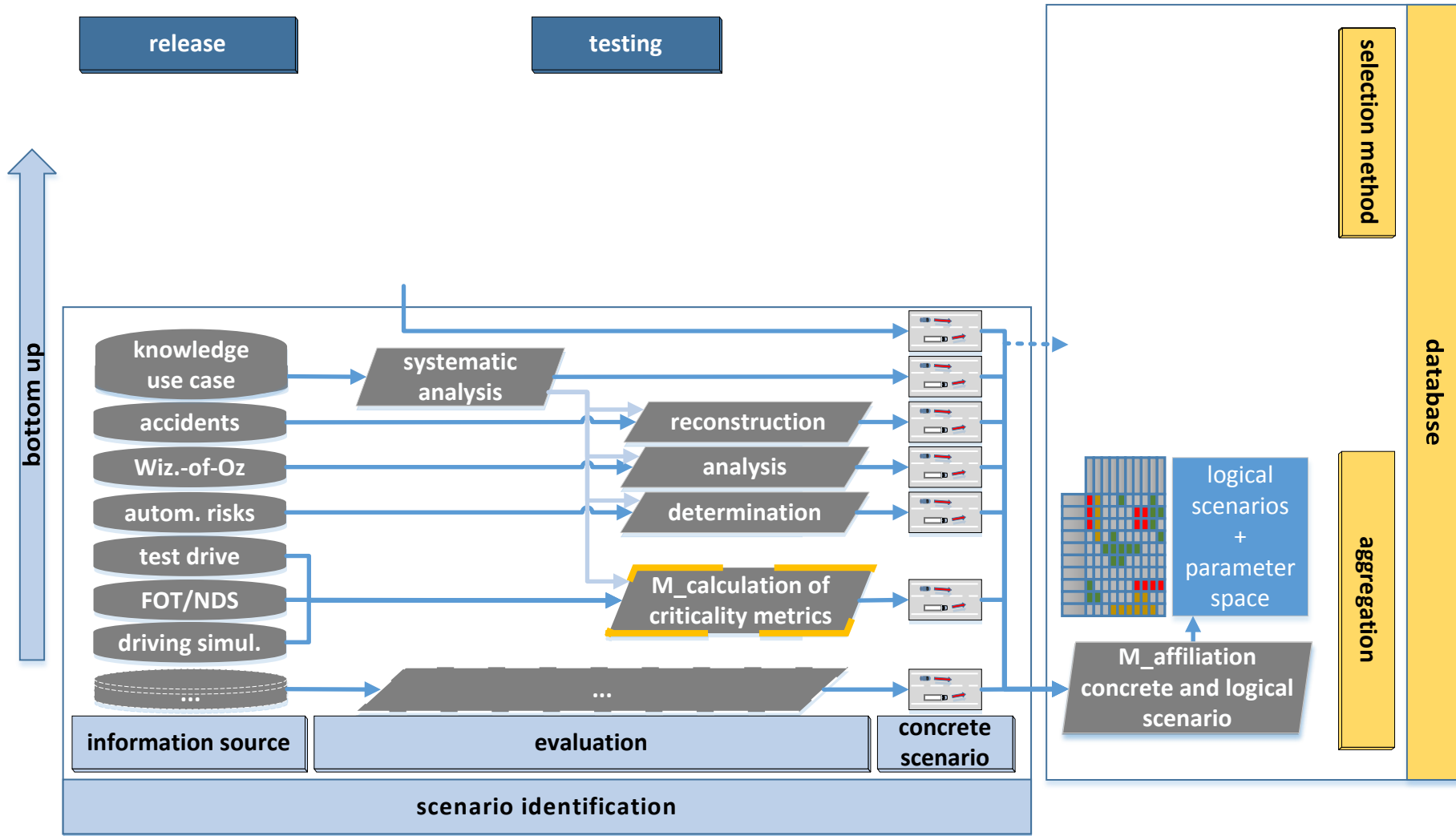


Metrics to Cluster Scenarios

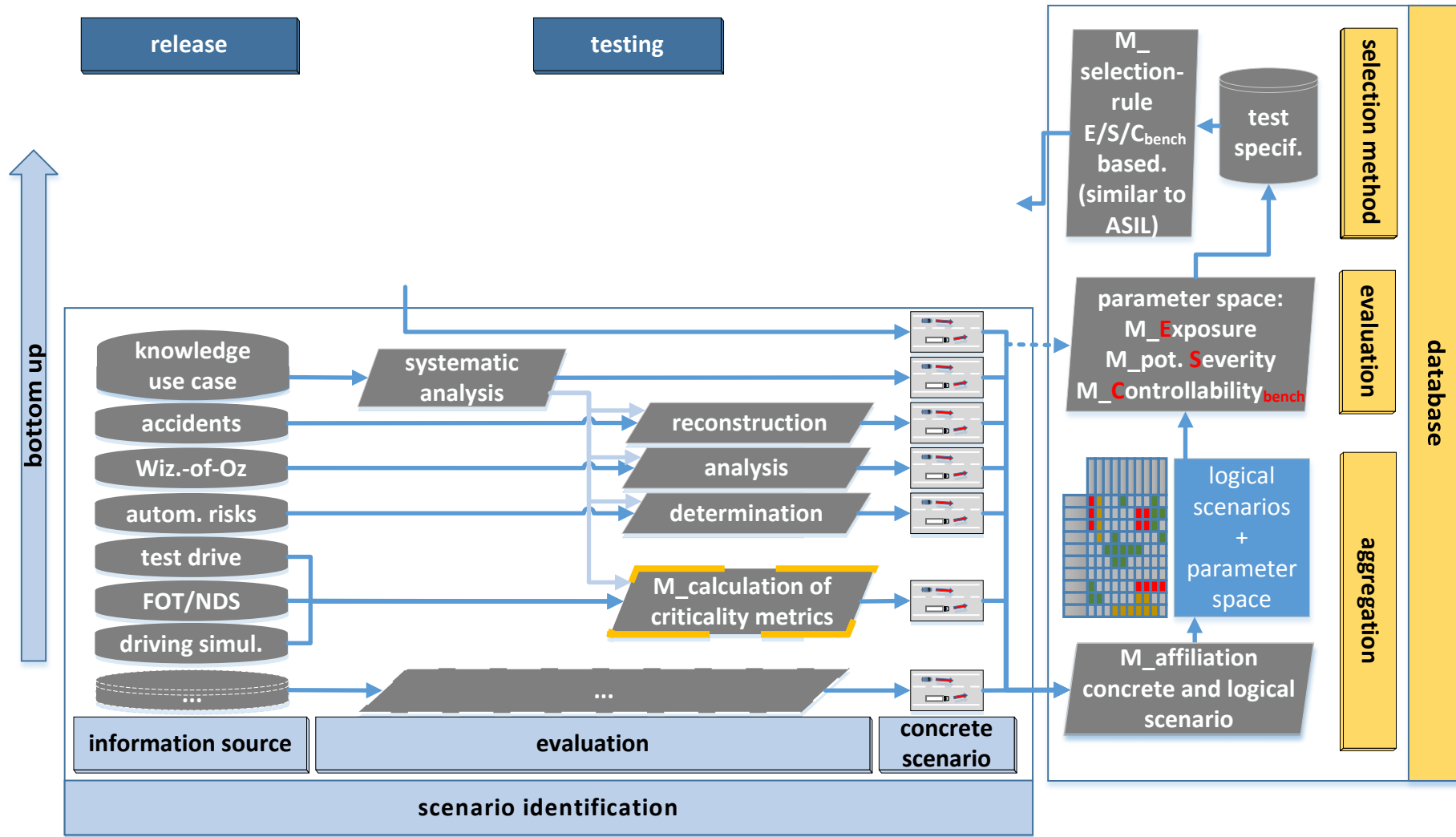
- affiliation concrete and logical scenario -



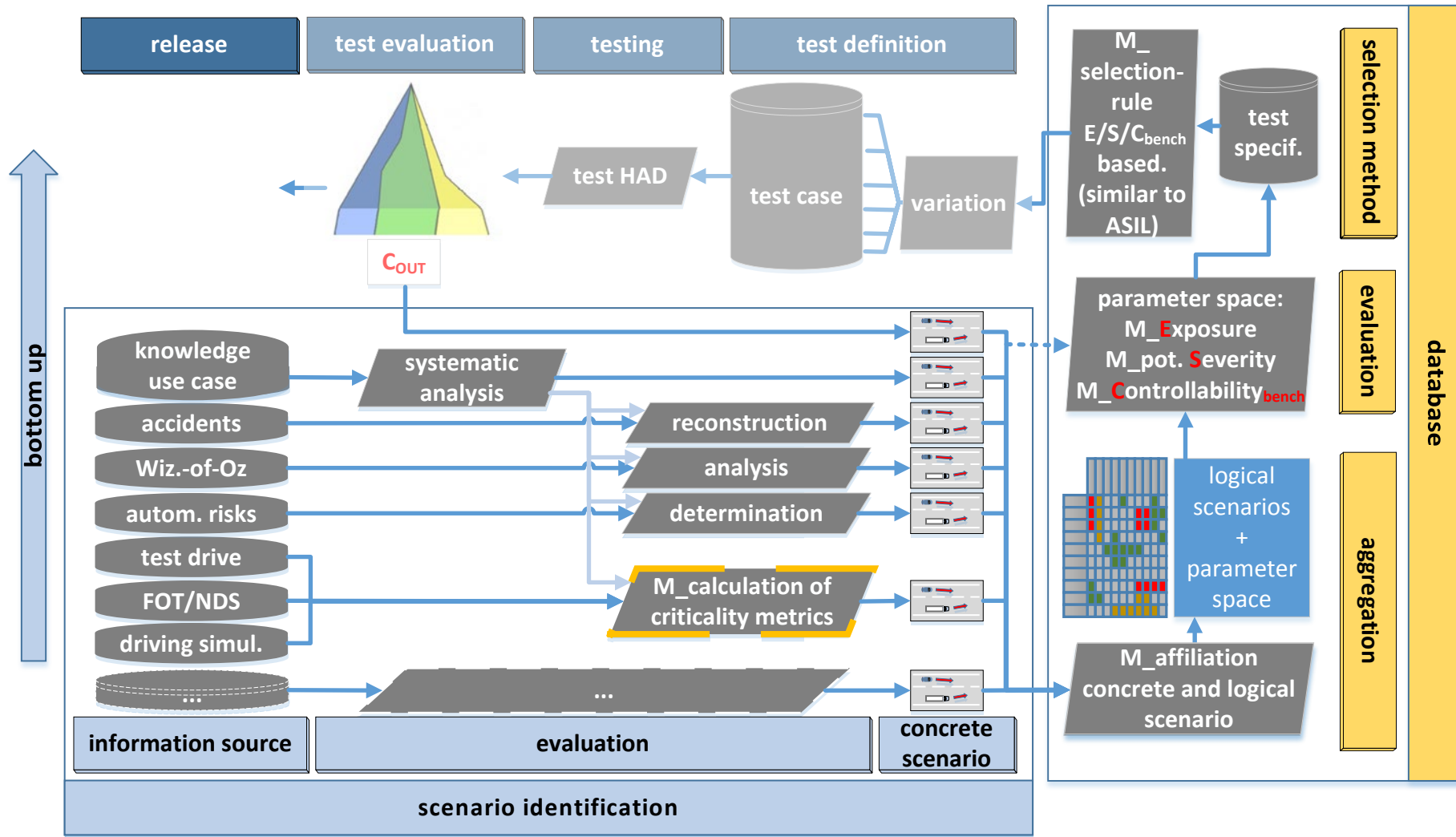
Method to Identify Scenarios and Assess Relevance



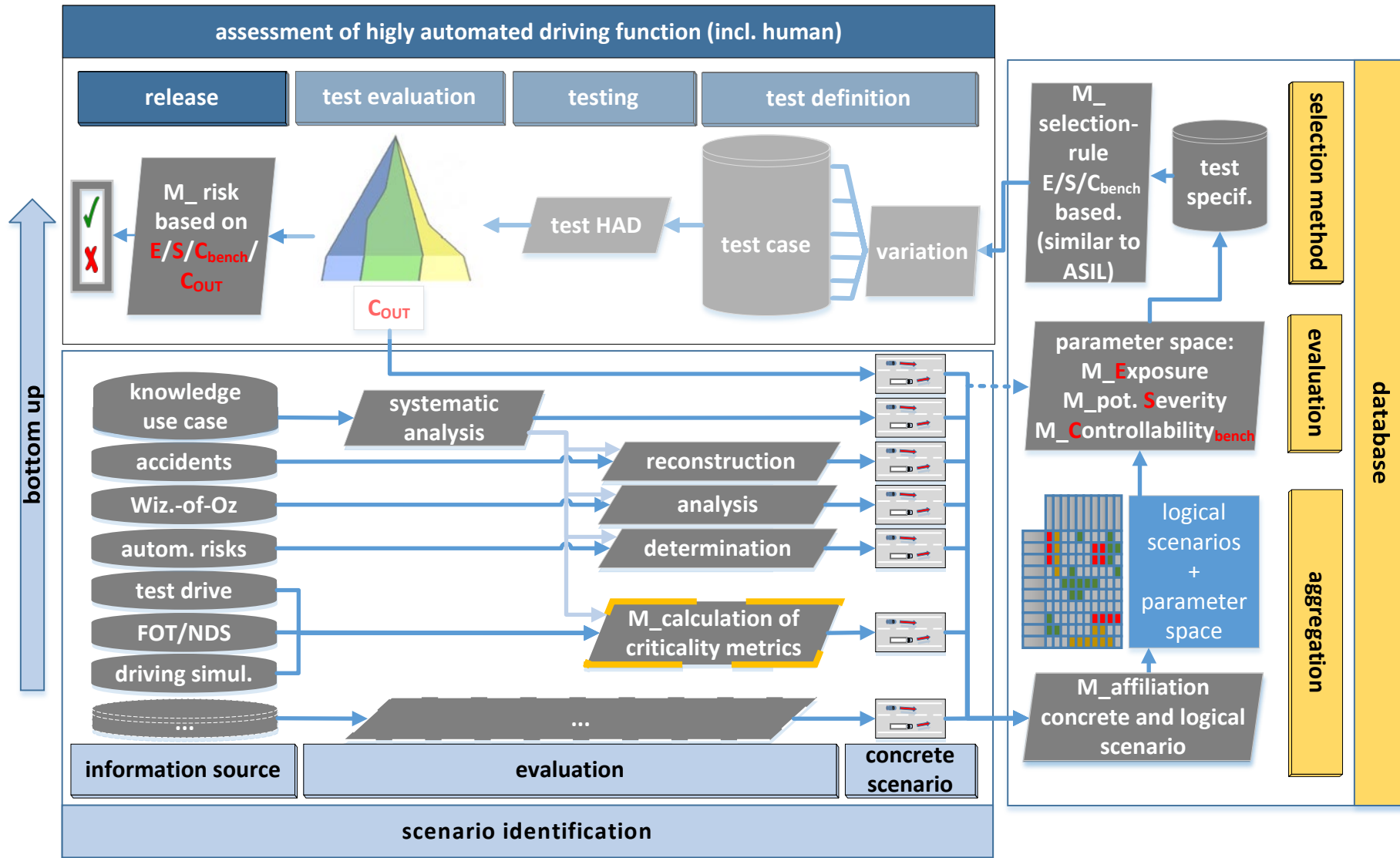
Method to Identify Scenarios and Assess Relevance



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Method to Identify Scenarios and Assess Relevance



Challenges:

- The amount and representativeness of data
 - How to define a logical scenario to represent the relevant reality in a consistent way?
 - How to demonstrate the validity of this approach?
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- An uncertainty on HAD's safety will remain for the first introduction.
 - The goal is to reduce this uncertainty to the best of today's knowledge.
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- Transferability to different use cases of HAD
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- PEGASUS starts with HAD on highways/Autobahn.
 - The transferability to further use cases will be studied within PEGASUS in the second step.

- The definition of a common method to identify scenarios is urgent.
- An approach has been proposed: the metric perspective
- The PEGASUS partners further work on this need.
- The final goal is a common scenario database as a transparent tool for collaboration
- The next steps are:
 - Further concretize the metrics
 - Gather information sources
 - Filling up the database



PEGASUS

- [1] Wachenfeld, Walther; Winner, Hermann (2016): The Release of Autonomous Vehicles. In Markus Maurer, J. Christian Gerdes, Barbara Lenz, Hermann Winner (Eds.): Autonomous Driving. Technical, Legal and Social Aspects: Springer, pp. 425–449.
- [2] Winner, Hermann; Wachenfeld, Walther (2013): Absicherung automatischen Fahrens. Presentation 6. Konferenz Fahrerassistenz in Munich.
- [3] Winner, Hermann (2016): ADAS, Quo Vadis? In Hermann Winner, Stephan Hakuli, Felix Lotz, Christina Singer (Eds.): Handbook of Driver Assistance Systems: Basic Information, Components and Systems for Active Safety and Comfort. Cham: Springer International Publishing, pp. 1557–1584.
- [4] Kalra, Nidhi; Paddock, Susan M. (2016): Driving to Safety: How Many Miles of Driving Would It Take to Demonstrate Autonomous Vehicle Reliability? RAND Corporation.
- [5] Ulbrich, Simon; Menzel, Till; Reschka, Andreas; Schuldt, Fabian; Maurer, Markus (2015): Defining and Substantiating the Terms Scene, Situation, and Scenario for Automated Driving: IEEE.
- [6] Wachenfeld, W., Junietz, P., Wenzel R., Winner, H. (2016) : The Worst-Time-To-Collision Metric for Situation Identification. Conference Paper and Poster IEEE Intelligent Vehicles Goteborg